Exercise - 2

21\_AIE\_213

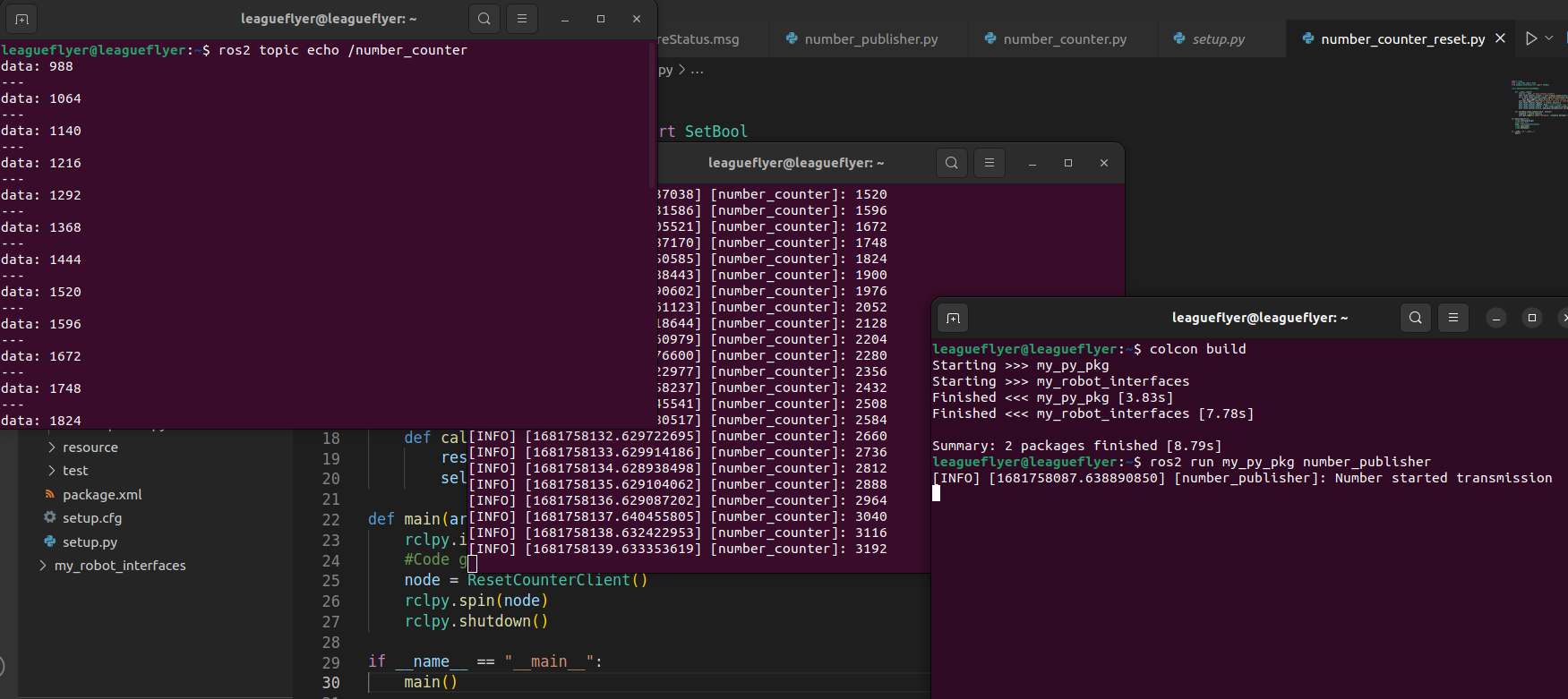
Robotics operating System– SEM-IV

Professor – Dr. Navneeth

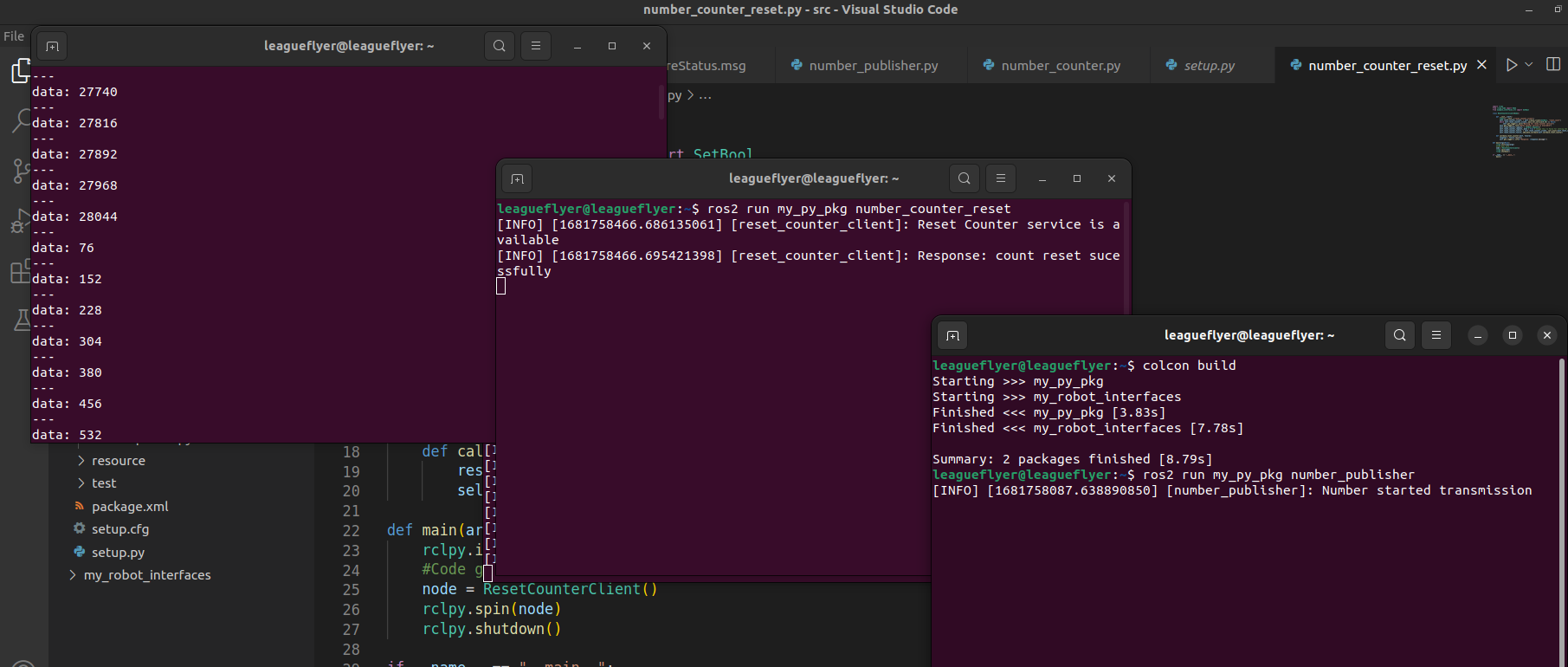
Submitted By: Vikhyat Bansal [CB.EN.U4AIE21076]

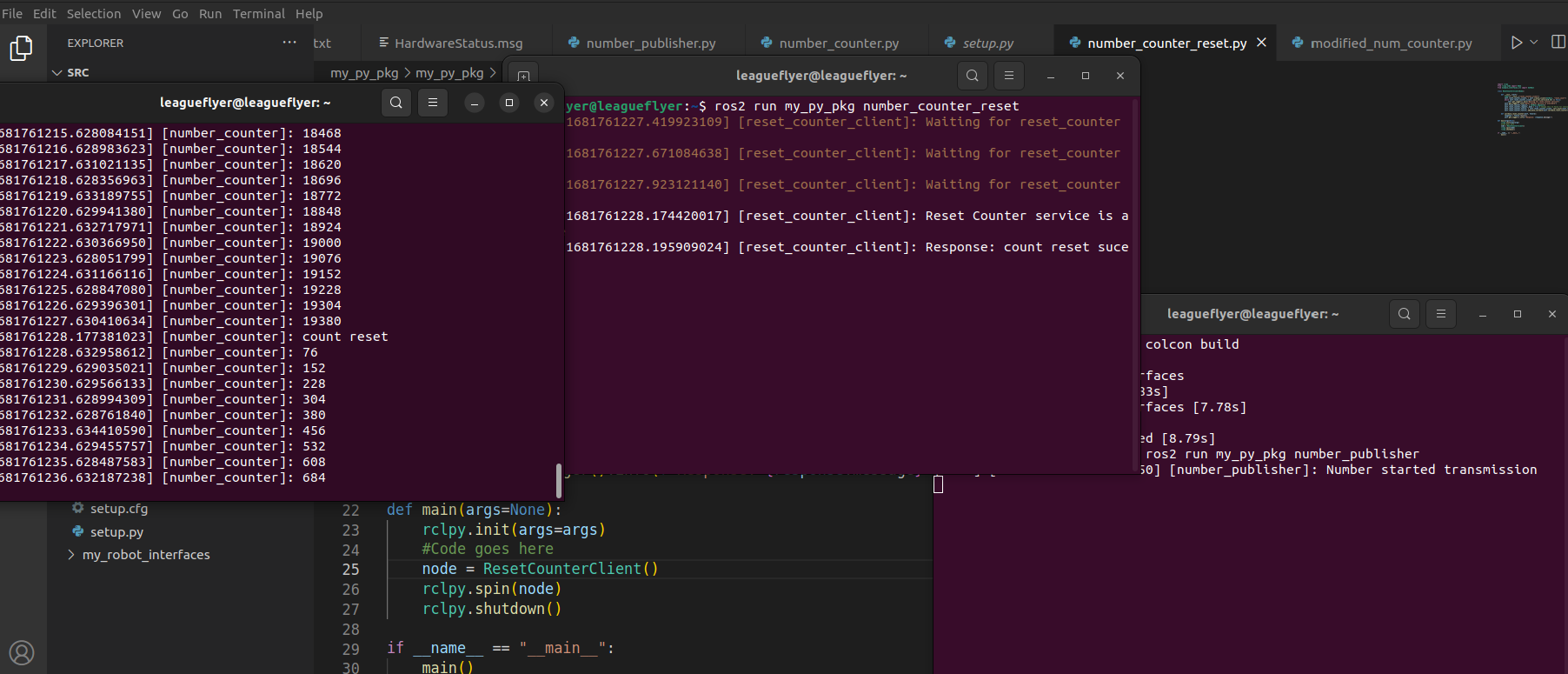


a) The number\_count topic output to the terminal using ros2 topic echo/number\_count without reset.

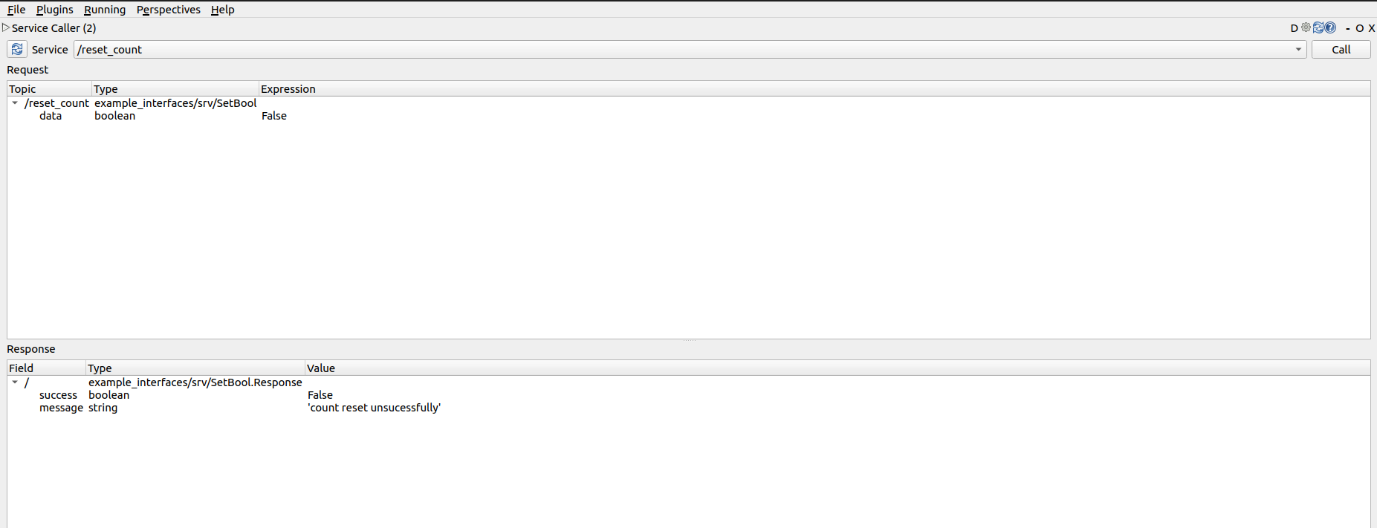


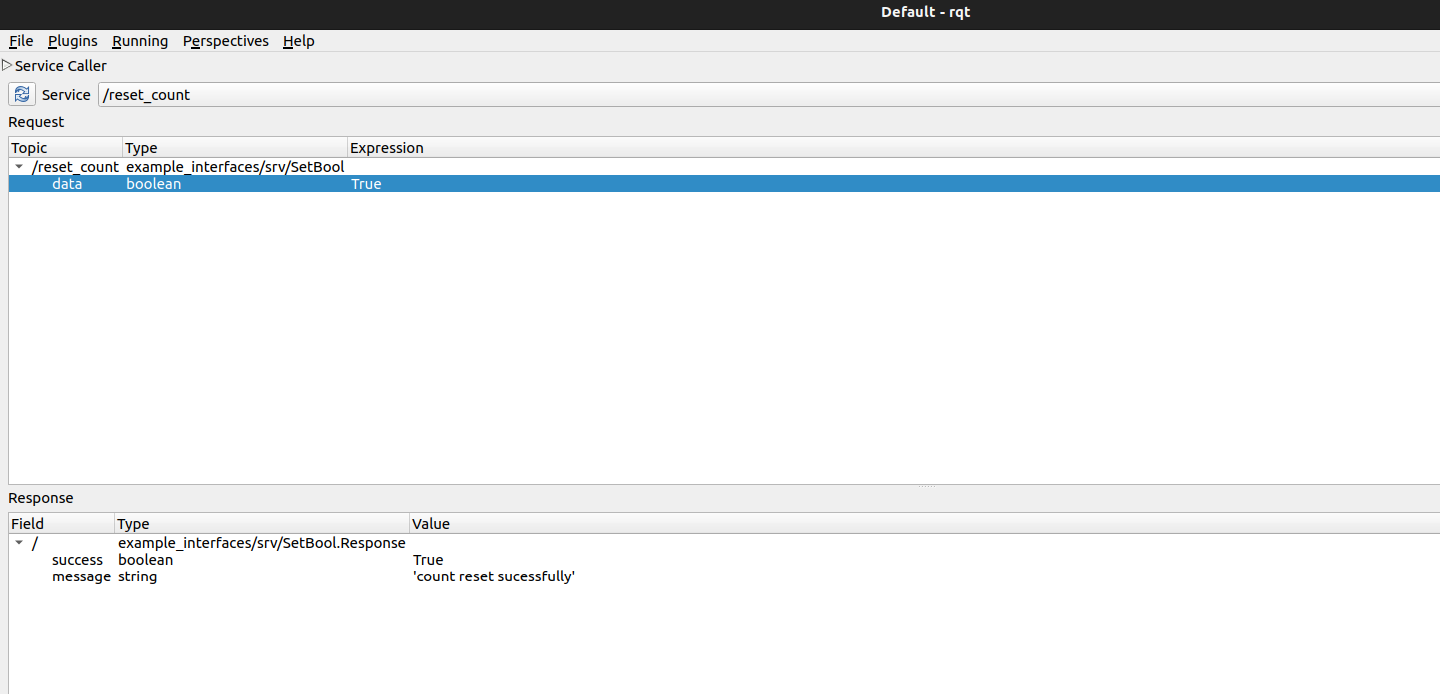
b) The number\_count topic output to the terminal using ros2 topic echo/number count with reset.





c) Request and response for counter value reset through rqt plugin.

False Condition:

True Condition: